

2506/202

2507/202

ELECTRONICS AND CONTROL SYSTEMS

Oct./Nov. 2022

Time: 3 hours



THE KENYA NATIONAL EXAMINATIONS COUNCIL

**DIPLOMA IN AERONAUTICAL ENGINEERING  
(AIRFRAMES AND ENGINES OPTION)  
(AVIONICS OPTION)**

**MODULE II**

ELECTRONICS AND CONTROL SYSTEMS

3 hours

**INSTRUCTIONS TO CANDIDATES**

*You should have the following for this examination:*

*Answer booklet;*

*Mathematical tables/Non-programmable scientific calculator;*

*Log-linear graph paper;*

*Drawing instruments.*

*This paper consists EIGHT questions in TWO sections; A and B.*

*Answer THREE questions from section A and TWO questions from section B in the answer booklet provided.*

*All questions carry equal marks.*

*Maximum marks for each part of a question are as indicated.*

*Candidates should answer the questions in English.*

**This paper consists of 7 printed pages and 1 insert.**

**Candidates should check the question paper to ascertain that all the pages are printed as indicated and that no questions are missing.**





### SECTION A: ELECTRONICS

Answer **THREE** questions from this section.

1. (a) Minimise each of the following logic expressions using Boolean algebra:

(i)  $f_1 = A\bar{C} + ABC + AC\bar{B}$

(ii)  $f_2 = Wyz + xy + x\bar{z} + yz$

(iii)  $f_3 = (w + x)(w + \bar{y})$

(7 marks)

- (b) Convert each of the following:

(i)  $(97.35)_{10}$  into binary (up to 5 binary points)

(ii)  $(74.075)_{10}$  into octal (up to 4 octal points)

(iii)  $(478.6)_{16}$  into octal.

(8 marks)

- (c) For a 2-to-4 decoder:

(i) draw the truth table;

(ii) draw the logic circuit diagram using NAND gates only.

(5 marks)

2. (a) (i) Distinguish between intrinsic and extrinsic semiconductors.

(ii) For a common-emitter transistor configuration, show that the current gains are related by:

$$\alpha = \frac{\beta}{1 + \beta}$$

(6 marks)

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- (b) Figure 1 shows a common-emitter transistor amplifier, where  $I_C = 100\mu A$ ,  $\beta = 100$ ,  $r_b = 0$ ,  $r_o = \infty$ ,  $r_{in} = \frac{I_C(MA)}{26}$ .

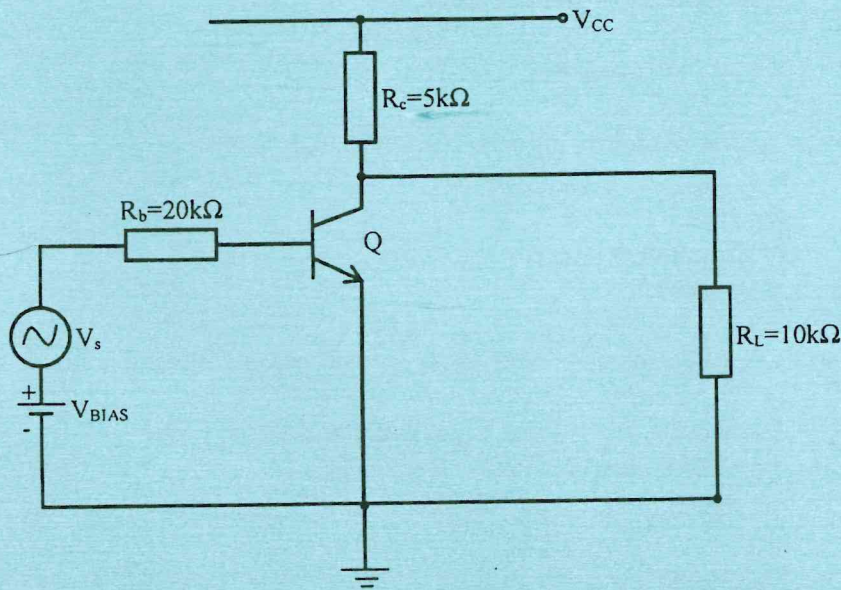


Fig. 1

- (i) Draw the small signal equivalent circuit of the amplifier.
- (ii) For the amplifier determine the:
- I. input resistance;
  - II. output resistance;
  - III. voltage gain. (9 marks)

- (c) With the aid of a voltage-current (V-I) characteristic curve, describe the operation of a silicon controlled rectifier (SCR). (5 marks)

3. (a) Draw the truth table for the following logic function:

$$f = xy + \bar{x}\bar{z} + yz \quad (4 \text{ marks})$$

- (b) Using a K-map, minimize the following Boolean expression:

$$f(A,B,C,D) = \Sigma(1,3,7,9,12,13,14,15) \quad (5 \text{ marks})$$

- (c) For each of the following expressions:

$$f_1(A, B, C) = \Sigma(0,4,5,7)$$

$$f_2(w, x, y, z) = \Sigma(0,3,7,10,12,14,15)$$





Implement each using:

- (i) 3-to-8 decoders and OR-gates;
- (ii) 8-to-1 multiplexers. (11 marks)

4. (a) Define each of the following with respect to logic gates:

- (i) fan-in;
- (ii) propagation delay;
- (iii) noise margin. (3 marks)

(b) A family of logic gates operates under the following voltage thresholds,

$$V_{OL} = 0.5V, V_{IL} = 1.6V, V_{OH} = 4.4V \text{ and } V_{IH} = 3.2V .$$

- (i) Sketch an input-output voltage transfer function for an inverter of the family.
- (ii) Determine the:
  - I. highest voltage for the inverter for a logic 0 output;
  - II. highest voltage for the inverter for a logic 1 output. (7 marks)

(c) Draw a circuit diagram of a CMOS inverter gate and describe its operation. (7 marks)

(d) State **three** merits of CMOS gates. (3 marks)

5. (a) With respect to sinusoidal oscillators:

- (i) define resonance;
- (ii) state Barkhausen criterion. (3 marks)

(b) With aid of circuit diagram, describe the operation of a transistor-based colpitt oscillator. (7 marks)

(c) State **three** characteristics of an ideal OP-Amp. (3 marks)





- (d) Figure 2 shows a circuit diagram of OP-Amp based system.

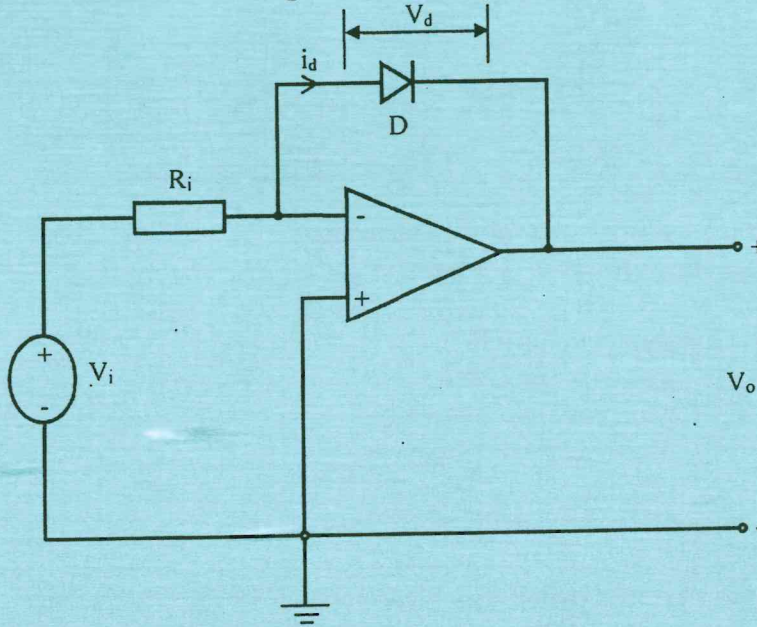


Fig. 2

- (i) Derive the expression for  $V_o$  in terms of  $V_i$  and  $R_i$ .
- (ii) Sketch the variation of  $V_o$  against  $V_i$ . (7 marks)

### SECTION B: CONTROL SYSTEMS

Answer *TWO* questions from this section.

6. (a) With aid of a diagram, explain the Nyquist stability criterion. (4 marks)
- (b) Explain each of the following with respect to system stability:
- (i) gain margin;
- (ii) phase margin. (4 marks)





(c) Table 1 shows the open loop response of a servo mechanism.

**Table 1**

$\omega$ (rad/s)	0.2	0.3	0.4	0.5	0.8	1.0	1.5	2	4	8	10	12
$ G $ dB	20	18	14	12	8	4.5	0	-4	-16	-30	-36	-40
$\angle G^\circ$	-95	-103	-105	-110	-120	-130	-145	-160	-195	-235	-245	-250

(i) Draw the Bode plot for the mechanism.

(ii) Determine from the plot the:

- I. gain margins (GM);
- II. phase margin (PM);
- III. gain cross-over frequency;
- IV. phase cross-over frequency.

(iii) Comment on the stability of the system.

(12 marks)

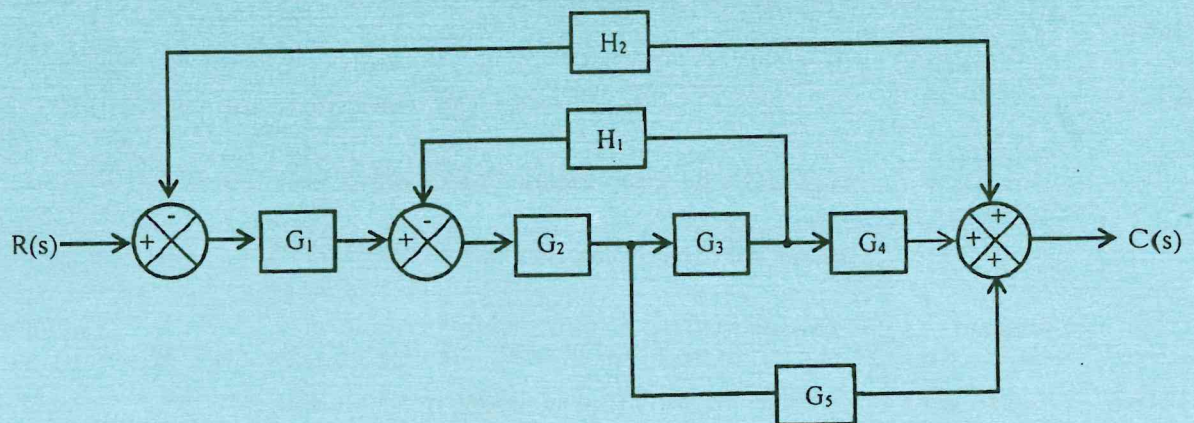
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7. (a) Define each of the following with respect to control systems:

- (i) disturbance;
- (ii) actuating signal.

(2 marks)

(b) Figure 3 shows a block diagram of a control system.



**Fig. 3**

(i) Draw a signal flow graph for the system.

(ii) Obtain the overall transfer function,  $C/R$ , of the system using Mason's gain formula.

(10 marks)





- (c) Figure 4 shows a block diagram of a unity feedback control system.

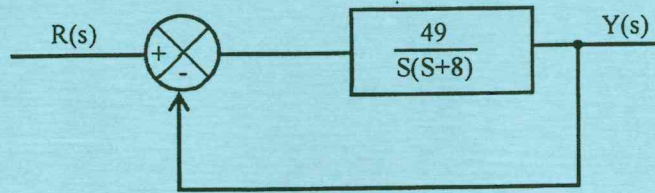


Fig. 4

Determine each of the following:

- (i) natural frequency,  $\omega_n$
- (ii) damping ratio,  $\varepsilon$
- (iii) setting time ( $T_s$ ), for 2% tolerance. (8 marks)

8. (a) State:

- (i) **two** reasons for avoiding differentiation in analogue computing;
- (ii) **three** reasons for time-scaling when solving computing problems using analogue computers. (5 marks)

- (b) A control system is represented by the following simultaneous differential equations:

$$\ddot{y} - 6\dot{y} - x = 0$$

$$\ddot{x} + 2\dot{x} - 3\dot{y} + x = 5$$

Draw an analogue computer flow diagram to solve the equations. (8 marks)

- (c) (i) Define each of the following with respect to stepper motors:

- I. step-angle;
- II. slewing.

- (ii) State **three** reasons for the widespread use of stepper motors in control systems.
- (iii) Sketch the typical static characteristics of a stepper motor showing the variation of the Torque ( $T$ ) against step angle ( $\theta$ ). (7 marks)

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Candidate Name: \_\_\_\_\_ Index No: \_\_\_\_\_

Semi-log Graph Paper

